Claims

- [c1] 1.A machining apparatus comprising: a discharge machining head assembly; and an electromagnet configured to support the head assembly in a position to machine an area.
- [02] 2. The apparatus of claim 1, wherein the head assembly has dimensions no larger than about 6.5 inches by about 9.6 inches by about 5.5 inches.
- [c3] 3. The apparatus of claim 1, wherein the head assembly has dimensions no larger than about 3.3 inches by about 4.8 inches by about 2.8 inches.
- [04] 4.The apparatus of claim 1, configured to have five axes of adjustment.
- [05] 5.The apparatus of claim 1, further comprising three manual slides configured to provide three axes of adjustment for the discharge machining head assembly.
- [66] 6. The apparatus of claim 1, further comprising a tilt and swivel vice configured to provide 2 axes of adjustment for the discharge machining head assembly.

- [c7] 7.The apparatus of claim 1, wherein the discharge machinchining head assembly is an electro-discharge machining head assembly.
- [08] 8.The apparatus of claim 1, wherein the discharge machining head assembly is an electrochemical discharge machining head assembly.
- [09] 9. The apparatus of claim 1 wherein the discharge machining head assembly is configured to drill a hole of up to about 12 mm in diameter.
- [c10] 10.An apparatus for machining comprising: a discharge machining head assembly; and a head assembly adaptor plate coupled to the discharge machining head assembly.
- [c11] 11.The apparatus of claim 10, wherein the adaptor plate is configured to also couple to a multi-axis robot arm.
- [c12] 12.The apparatus of claim 10, wherein the apparatus has dimensions no larger than about 6.5 inches by about 9.6 inches by about 5.5 inches.
- [c13] 13.The apparatus of claim 10, wherein the apparatus has dimensions no larger than about 3.3 inches by about 4.8 inches by about 2.8 inches.
- [c14] 14.The apparatus of claim 10, wherein the discharge

- machining head assembly is an electro-discharge machining head assembly.
- [c15] 15.The apparatus of claim 10, wherein the discharge machining head assembly is an electrochemical discharge machining head assembly.
- [c16] 16.The apparatus of claim 10 wherein the discharge machining head assembly is configured to drill a hole of about 12 mm in diameter.
- [017] 17.An apparatus for machining comprising: a discharge machining head assembly; a sliding assembly coupled to the discharge machining head assembly; and a sliding assembly adaptor plate coupled to the sliding assembly.
- [c18] 18.The apparatus of claim 17, wherein the adaptor plate is configured to couple to a multi-axis robot arm.
- [c19] 19.The apparatus of claim 17, wherein the head assembly has dimensions no larger than about 6.5 inches by about 9.6 inches by about 5.5 inches.
- [c20] 20.The apparatus of claim 15, wherein the head assembly has dimensions no larger than about 3.3 inches by about 4.8 inches by 2.8 about inches.

- [c21] 21.The apparatus of claim 17 configured to have 5 axes of adjustment.
- [022] 22.The apparatus of claim 17, wherein the sliding assembly comprises three manual slides which are configured to provide 3 axes of adjustment to the discharge machining head assembly.
- [023] 23.The apparatus of claim 17, wherein the slide assembly comprises a tilt and swivel vice which is configured to provide 2 axes of adjustment to the discharge machining head assembly.
- [c24] 24.The apparatus of claim 17, wherein the discharge machining head assembly is an electro-discharge machining head assembly.
- [c25] 25.The apparatus of claim 17, wherein the discharge machining head assembly is an electrochemical discharge machining head assembly.
- [c26] 26.The apparatus of claim 17 wherein the discharge machining head assembly is configured to drill a hole of about 12 mm in diameter.
- [027] 27.An apparatus for guiding a drill electrode comprising: a bushing; an insulated annulus located in the bushing; and

- a bushing holder coupled to the bushing.
- [c28] 28.The apparatus of claim 27, wherein the bushing holder is a magnetic base.
- [c29] 29.A method for machining comprising:
 attaching a machining tool to a surface;
 positioning a drill electrode to a work piece; and
 drilling the work piece with the machining tool.
- [c30] 30.The method of claim 29 wherein the attaching act comprises: magnetically attaching a machining tool to a surface.
- [c31] 31.The method of claim 29 wherein the positioning act comprises: adjusting a 5 axis slide assembly to position the drill electrode.
- [032] 32.The method of claim 29, wherein the drilling act comprises: drilling the work piece with the machining tool using electro-discharge machining.
- [c33] 33.The method of claim 29, wherein the drilling act comprises: drilling the work piece with the machining tool using electrochemical discharge machining.

[c34] 34.The method of claim 29, wherein the drilling act comprises:drilling out a stator blade pin with the machining tool.